
Guidance for Industry

SUPAC: Manufacturing Equipment Addendum

DRAFT GUIDANCE

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**U.S. Department of Health and Human Services
Food and Drug Administration
Center for Drug Evaluation and Research (CDER)**

**April 2013
CMC**

Contains Nonbinding Recommendations

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Guidance for Industry

SUPAC: Manufacturing Equipment Addendum

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TABLE OF CONTENTS

I.	INTRODUCTION.....	1
II.	BACKGROUND	2
III.	DISCUSSION	2
IV.	SUPAC IR/MR INFORMATION.....	3
	A. Particle Size Reduction/Separation.....	3
	1. <i>Definitions</i>	3
	2. <i>Equipment Classifications</i>	4
	B. Blending and Mixing	6
	1. <i>Definitions</i>	6
	2. <i>Equipment Classifications</i>	6
	C. Granulation.....	7
	1. <i>Definitions</i>	7
	2. <i>Equipment Classification</i>	9
	D. Drying.....	10
	1. <i>Definitions</i>	10
	2. <i>Equipment Classifications</i>	12
	E. Unit Dosing.....	14
	1. <i>Definitions</i>	14
	2. <i>Equipment Classifications</i>	15
	F. Soft Gelatin Capsule.....	16
	1. <i>Definitions</i>	16
	2. <i>Equipment Classifications</i>	18
	G. Coating/Printing/Drilling.....	19
	1. <i>Definitions</i>	19
	2. <i>Equipment Classification</i>	22
V.	SUPAC-SS INFORMATION.....	23
	A. Particle Size Reduction/Separation.....	23
	1. <i>Definitions</i>	23
	2. <i>Equipment Classifications</i>	24

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B. Mixing	26
1. <i>Definitions</i>	26
2. <i>Equipment Classification</i>	26
C. Emulsification	27
1. <i>Definitions</i>	27
2. <i>Equipment Classification</i>	28
D. Deaeration	28
1. <i>Definitions</i>	28
2. <i>Equipment Classification</i>	28
E. Transfer	29
1. <i>Definition</i>	29
2. <i>Equipment Classification</i>	29
F. Packaging	30
1. <i>Definitions</i>	30
2. <i>Equipment Classification</i>	30

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SUPAC: Manufacturing Equipment Addendum

This draft guidance, when finalized, will represent the Food and Drug Administration's (FDA's) current thinking on this topic. It does not create or confer any rights for or on any person and does not operate to bind FDA or the public. You can use an alternative approach if the approach satisfies the requirements of the applicable statutes and regulations. If you want to discuss an alternative approach, contact the FDA staff responsible for implementing this guidance. If you cannot identify the appropriate FDA staff, call the appropriate number listed on the title page of this guidance.

I. INTRODUCTION

This draft guidance combines and supersedes the following scale-up and post-approval changes (SUPAC) guidances for industry: (1) *SUPAC-IR/MR: Immediate Release and Modified Release Solid Oral Dosage Forms, Manufacturing Equipment Addendum*, and (2) *SUPAC-SS Nonsterile Semisolid Dosage Forms, Manufacturing Equipment Addendum*.² It removes the lists of manufacturing equipment that were in both guidances and clarifies the types of processes being referenced.

This draft SUPAC addendum should be used in conjunction with the following SUPAC guidances for industry:³ (1) *Immediate Release Solid Oral Dosage Forms — Scale-Up and Post-Approval Changes: Chemistry, Manufacturing and Controls, In Vitro Dissolution Testing, and In Vivo Bioequivalence Documentation*, (2) *SUPAC-MR: Modified Release Solid Oral Dosage Forms Scale-Up and Post-Approval Changes: Chemistry, Manufacturing and Controls; In Vitro Dissolution Testing and In Vivo Bioequivalence Documentation*, and (3) *SUPAC-SS: Nonsterile Semisolid Dosage Forms, Scale-Up and Post Approval Changes: Chemistry Manufacturing and Controls; In Vitro Release Testing and In Vivo Bioequivalence Documentation*.⁴

The SUPAC guidances define: (1) levels of chemistry, manufacturing, and control change; (2) recommended chemistry, manufacturing, and controls tests for each level of change; (3) recommended in vitro dissolution and release tests and/or in vivo bioequivalence tests for each level of change; and (4) recommended documentation that should support the change for new drug applications and abbreviated new drug applications.

¹ This guidance has been prepared by the Office of Pharmaceutical Science in the Center for Drug Evaluation and Research (CDER) at the Food and Drug Administration.

² For this guidance only, the new document that is a combination of these two guidances will be referred to as the *SUPAC addendum*.

³ We update guidances periodically. To make sure you have the most recent version of a guidance, check the FDA Drugs guidance Web page at <http://www.fda.gov/Drugs/GuidanceComplianceRegulatoryInformation/Guidances/default.htm>.

⁴ For this guidance only, this collective group of guidances will be referred to as *SUPAC guidances*.

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40 This draft SUPAC addendum, together with the SUPAC guidances, is intended to help you, the
41 manufacturer, determine the documentation you should submit to FDA regarding manufacturing
42 equipment changes.

43
44 FDA's guidance documents, including this guidance, do not establish legally enforceable
45 responsibilities. Instead, guidances describe the Agency's current thinking on a topic and should
46 be viewed only as recommendations, unless specific regulatory or statutory requirements are
47 cited. The use of the word *should* in Agency guidances means that something is suggested or
48 recommended, but not required.

II. BACKGROUND

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51
52 When the SUPAC equipment addenda were published with tables referencing specific
53 equipment, the tables were misinterpreted as equipment required by FDA. FDA recognizes
54 that scientific innovation and technology advancement are commonplace and play a significant
55 role in pharmaceutical development, manufacturing, and quality assurance, and we are
56 concerned that such a misunderstanding could discourage advancements in manufacturing
57 technologies. Therefore, this revised draft SUPAC addendum contains general information on
58 SUPAC equipment and no longer includes tables referencing specific equipment. This draft
59 guidance also includes changes to clarify the types of processes being referenced.

III. DISCUSSION

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63 The information in this draft guidance is presented in broad categories of unit operation. For
64 immediate or modified release solid oral dosage forms, broad categories include blending and
65 mixing, drying, particle size reduction/separation, granulation, unit dosage, coating and printing,
66 and soft gelatin capsule encapsulation. For nonsterile semisolid dosage forms, broad categories
67 include particle size reduction and/or separation, mixing, emulsification, deaeration, transfer, and
68 packaging. Definitions and classifications are provided. For each operation, equipment is
69 categorized by class (operating principle) and subclass (design characteristic). Examples of types
70 of equipment, but not specific brand information, are given within the subclasses.

71
72 When assessing manufacturing equipment changes from one class to another or from one
73 subclass to another, you can follow a risk-based approach that includes a rationale and complies
74 with the regulations, including the CGMP regulations.^{5, 6} We also recommend addressing the
75 impact on the product quality attributes of equipment variations (via process parameters) when
76 designing and developing the manufacturing process.

77
78 When making equipment changes, you will need to determine the filing requirement.⁷ The
79 SUPAC guidances provide information on how to do so. FDA will assess the changes based on
80 the types of equipment changes being considered. If you choose an approach that exceeds the
81 SUPAC guidances and addendum, FDA will assess the changes provided they are supported by
82 a suitable risk-based assessment.

⁵ 21 CFR 314.70.

⁶ 21 CFR 210-211.

⁷ 21 CFR 314.70.

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83 At the time of the equipment change, you should have available the scientific data and rationale
84 used to determine the type of change and documentation required. This information is subject to
85 FDA review at its discretion.

86

87 **IV. SUPAC IR/MR INFORMATION**

88

89 **A. Particle Size Reduction/Separation**

90

91 *1. Definitions*

92

93 *a. Unit Operations*

94

95 *i. Particle Size Reduction: The mechanical process of breaking particles into*
96 *smaller pieces via one or more particle size reduction mechanisms. The*
97 *mechanical process used generally is referred to as milling.*

98

99 *a. Particle – Refers to either a discrete particle or a grouping of particles,*
100 *generally know as an agglomerate.*

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ii. Particle Separation: Particle size classification according to particle size
alone.

b. Operating Principles

i. Fluid Energy Milling

Particles are reduced in size as a result of high-speed particle-to-particle
impact and/or attrition; also known as micronizing.

ii. Impact Milling

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Particles are reduced in size by high-speed mechanical impact or impact with other particles; also known as milling, pulverizing, or comminuting.

iii. Cutting

Particles are reduced in size by mechanical shearing.

iv. Compression Milling

Particles are reduced in sized by compression stress and shear between two surfaces.

v. Screening

Particles are reduced in size by mechanically induced attrition through a screen. This process commonly is referred to as milling or deagglomeration.

vi. Tumble Milling

Particles are reduced in size by attrition utilizing grinding media.

vii. Separating

Particles are segregated based upon particle size alone and without any significant particle size reduction. This process commonly is referred to as screening or bolting.

2. Equipment Classifications

a. Fluid Energy Mills

Fluid energy mill subclasses have no moving parts and primarily are distinguished from one another by the configuration and/or shape of their chambers, nozzles, and classifiers.

- Tangential Jet
- Loop/Oval
- Opposed Jet
- Opposed Jet with Dynamic Classifier
- Fluidized Bed
- Fixed Target
- Moving Target
- High Pressure Homogenizer

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b. Impact Mills

Impact mill subclasses primarily are distinguished from one another by the configuration of the grinding heads, chamber grinding liners (if any), and classifiers.

- Hammer Air Swept
- Hammer Conventional
- Pin/Disc
- Cage

c. Cutting Mills

Although cutting mills may differ from one another in whether the knives are movable or fixed and in the classifier configuration, no cutting mill subclasses have been identified.

d. Compression Mills

Although compression mills may differ from one another in whether one or both surfaces are moving, no compression mill subclasses have been identified.

e. Screening Mills

Screening mill subclasses primarily are distinguished from one another by the rotating element.

- Rotating Impeller
- Rotating Screen
- Oscillating Bar

f. Tumbling Mills

Tumbling mill subclasses primarily are distinguished from one another by the grinding media used and by whether the mill is vibrated.

- Ball Media
- Rod Media
- Vibrating

g. Separators

Separator subclasses primarily are distinguished from one another by the mechanical means used to induce particle movement.

- Vibratory/Shaker
- Centrifugal

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B. Blending and Mixing

1. Definitions

a. Unit Operations

Blending and Mixing: The reorientation of particles relative to one another in order to achieve uniformity.

b. Operating Principles

i. Diffusion Blending (Tumble)

Particles are reoriented in relation to one another when they are placed in random motion and interparticular friction is reduced as the result of bed expansion (usually within a rotating container); also known as tumble blending.

ii. Convection Mixing

Particles are reoriented in relation to one another as a result of mechanical movement; also known as paddle or plow mixing.

iii. Pneumatic Mixing

Particles are reoriented in relation to one another as a result of the expansion of a powder bed by gas.

2. Equipment Classifications

a. Diffusion Mixers (Tumble)

Diffusion mixer subclasses primarily are distinguished by geometric shape and the positioning of the axis of rotation.

- V-blenders
- Double Cone Blenders
- Slant Cone Blenders
- Cube Blenders
- Bin Blenders
- Horizontal/Vertical/Drum Blenders
- Static Continuous Blenders
- Dynamic Continuous Blenders

b. Convection Mixers

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270
271 Convection blender subclasses primarily are distinguished by vessel shape and
272 impeller geometry.

- 273
274
- Ribbon Blenders
 - Orbiting Screw Blenders
 - Planetary Blenders
 - Forberg Blenders
 - Horizontal Double Arm Blenders
 - Horizontal High Intensity Mixers
 - Vertical High Intensity Mixers
 - Diffusion Mixers (Tumble) with Intensifier/Agitator

282
283 c. Pneumatic Mixers

284
285 Although pneumatic mixers may differ from one another in vessel geometry, air
286 nozzle type, and air nozzle configuration, no pneumatic mixer subclasses have
287 been identified.

288
289

C. Granulation

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292 1. *Definitions*

293
294 a. Unit Operations

295
296 Granulation: The process of creating granules. The powder morphology is
297 modified through the use of either a liquid that causes particles to bind through
298 capillary forces or dry compaction forces. The process will result in one or more
299 of the following powder properties: enhanced flow; increased compressibility;
300 densification; alteration of physical appearance to more spherical, uniform, or
301 larger particles; and/or enhanced hydrophilic surface properties.

302
303 b. Operating Principles

304
305 i. Dry Granulation

306
307 Dry powder densification and/or agglomeration by direct
308 physical compaction.

309
310 ii. Wet High-Shear Granulation

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312 Powder densification and/or agglomeration by the incorporation
313 of a granulation fluid into the powder with high-power-per-unit
314 mass, through rotating high-shear forces.

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- iii. Wet Low-Shear Granulation
Powder densification and/or agglomeration by the incorporation of a granulation fluid into the powder with low-power-per-unit mass, through rotating low-shear forces.
 - iv. Low-Shear Tumble Granulation
Powder densification and/or agglomeration by the incorporation of a granulation fluid into the powder with low-power-per-unit mass, through rotation of the container vessel and/or intensifier bar.
 - v. Extrusion Granulation
Plasticization of solids or wetted mass of solids and granulation fluid with linear shear through a sized orifice using a pressure gradient.
 - vi. Rotary Granulation
Spheronization, agglomeration, and/or densification of a wetted or non-wetted powder or extruded material. This is accomplished by centrifugal or rotational forces from a central rotating disk, rotating walls, or both. The process may include the incorporation and/or drying of a granulation fluid.
 - vii. Fluid Bed Granulation
Powder densification and/or agglomeration with little or no shear by direct granulation fluid atomization and impingement on solids, while suspended by a controlled gas stream, with simultaneous drying.
 - viii. Spray Dry Granulation
A pumpable granulating liquid containing solids (in solution or suspension) is atomized in a drying chamber and rapidly dried by a controlled gas stream, producing a dry powder.
 - ix. Hot-melt Granulation
An agglomeration process that utilizes a molten liquid as a binder(s) or granulation matrix in which the active pharmaceutical ingredient (API) is mixed and then cooled down followed by milling into powder. This is usually accomplished in a temperature controlled jacketed high shear granulating tank

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363 or using a heated nozzle that sprays the molten binders(s) onto
364 the fluidizing bed of the API and other inactive ingredients.
365

2. *Equipment Classification*

a. Dry Granulator

367
368 Dry granulator subclasses primarily are distinguished by the densification force
369 application mechanism.
370
371

- 372 • Slugging
- 373 • Roller Compaction
- 374
- 375

b. Wet High-Shear Granulator

376
377 Wet high-shear granulator subclasses primarily are distinguished by the
378 geometric positioning of the primary impellers; impellers can be top, bottom,
379 or side driven.
380

- 381 • Vertical (Top or Bottom Driven)
- 382 • Horizontal (Side Driven)
- 383
- 384

c. Wet Low-Shear Granulator

385
386 Wet low-shear granulator subclasses primarily are distinguished by the
387 geometry and design of the shear inducing components; shear can be induced
388 by rotating impeller, reciprocal kneading action, or convection screw action.
389

- 390 • Planetary
- 391 • Kneading
- 392 • Screw
- 393
- 394

d. Low-Shear Tumble Granulator

395
396 Although low-shear tumble granulators may differ from one another in vessel
397 geometry and type of dispersion or intensifier bar, no low-shear tumble
398 granulator subclasses have been identified.
399

- 400 • Slant cone
- 401 • Double cone
- 402 • V-blender
- 403
- 404

e. Extrusion Granulator

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407 Extrusion granulator subclasses primarily are distinguished by the
408 orientation of extrusion surfaces and driving pressure production
409 mechanism.

- 410
- 411 • Radial or Basket
 - 412 • Axial
 - 413 • Ram
 - 414 • Roller, Gear, or Pelletizer
- 415

416 f. Rotary Granulator

417

418 Rotary granulator subclasses primarily are distinguished by their structural
419 architecture. They have either open top architecture, such as a vertical centrifugal
420 spheronizer, or closed top architecture, such as a closed top fluid bed dryer.

- 421
- 422 • Open
 - 423 • Closed
- 424

425 g. Fluid Bed Granulator

426

427 Although fluid bed granulators may differ from one another in geometry,
428 operating pressures, and other conditions, no fluid bed granulator subclasses
429 have been identified.

430

431 h. Spray Dry Granulator

432

433 Although spray dry granulators may differ from one another in geometry,
434 operating pressures, and other conditions, no spray dry granulator subclasses have
435 been identified.

436

437 i. Hot-melt Granulator

438

439 Although, hot-melt granulator may differ from one another in primarily melting the
440 inactive ingredient (particularly the binder or other polymeric matrices), no
441 subclasses have been indentified yet.

442

443 Note:

444 If a single piece of equipment is capable of performing multiple discrete unit operations (mixing,
445 granulating, drying), the unit was evaluated solely for its ability to granulate. If multifunctional
446 units were incapable of discrete steps (fluid bed granulator/drier), the unit was evaluated as an
447 integrated unit.

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449 **D. Drying**

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451 *1. Definitions*

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a. Unit Operation

Drying: The removal of a liquid from a solid by evaporation.

b. Operating Principles

i. Direct Heating, Static Solids Bed

Heat transfer is accomplished by direct contact between the wet solids and hot gases. The vaporized liquid is carried away by the drying gases. There is no relative motion among solid particles. The solids bed exists as a dense bed, with the particles resting upon one another.

ii. Direct Heating, Moving Solids Bed

Heat transfer is accomplished by direct contact between the wet solids and hot gases. The vaporized liquid is carried away by the drying gases. Solids motion is achieved by either mechanical agitation or gravity force, which slightly expands the bed enough to flow one particle over another.

iii. Direct Heating, Fluidized Solids Bed

Heat transfer is accomplished by direct contact between the wet solids and hot gases. The vaporized liquid is carried away by the drying gases. The solids are in an expanded condition, with the particles supported by drag forces caused by the gas phase. The solids and gases intermix and behave like a boiling liquid. This process commonly is referred to as fluid bed drying.

iv. Direct Heating, Dilute Solids Bed, Spray Drying

Heat transfer is accomplished by direct contact between a highly dispersed liquid and hot gases. The feed liquid may be a solution, slurry, emulsion, gel or paste, provided it is pumpable and capable of being atomized. The fluid is dispersed as fine droplets into a moving stream of hot gases, where they evaporate rapidly before reaching the wall of the drying chamber. The vaporized liquid is carried away by the drying gases. The solids are fully expanded and so widely separated that they exert essentially no influence on one another.

v. Direct Heating, Dilute Solids Bed, Flash Drying

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498 Heat transfer is accomplished by direct contact between wet solids
499 and hot gases. The solid mass is suspended in a finely divided state
500 in a high-velocity and high-temperature gas stream. The vaporized
501 liquid is carried away by the drying gases.

502

503 vi. Indirect Conduction, Moving Solids Bed

504

505 Heat transfer to the wet solid is through a retaining wall. The
506 vaporized liquid is removed independently from the heating
507 medium. Solids motion is achieved by either mechanical agitation
508 or gravity force, which slightly expands the bed enough to flow one
509 particle over another.

510

511 vii. Indirect Conduction, Static Solids Bed

512

513 Heat transfer to the wet solid is through a retaining wall. The
514 vaporized liquid is removed independently from the heating
515 medium. There is no relative motion among solid particles. The
516 solids bed exists as a dense bed, with the particles resting upon one
517 another.

518

519 viii. Indirect Conduction, Lyophilization

520

521 Drying in which the water vapor sublimates from the product after
522 freezing.

523

524 ix. Gas Stripping

525

526 Heat transfer is a combination of direct and indirect heating. The
527 solids motion is achieved by agitation and the bed is partially
528 fluidized.

529

530 x. Indirect Radiant, Moving Solids Bed

531

532 Heat transfer is accomplished with varying wavelengths of energy.
533 Vaporized liquid is removed independently from the solids bed.
534 The solids motion is achieved by mechanical agitation, which
535 slightly expands the bed enough to flow one particle over one
536 another. This process commonly is referred to as microwave
537 drying.

538

539 2. *Equipment Classifications*

540

541 a. Direct Heating, Static Solids Bed

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- 543 Static solids bed subclasses primarily are distinguished by the method of
544 moving the solids into the dryer.
545
- 546 • Tray and Truck
 - 547 • Belt
- 548
- 549 b. Direct Heating, Moving Solids Bed
- 550
- 551 Moving solids bed subclasses primarily are distinguished by the method or
552 technology for moving the solids bed.
553
- 554 • Rotating Tray
 - 555 • Horizontal Vibrating Conveyor
- 556
- 557 c. Direct Heating, Fluidized Solids Bed (Fluid Bed Dryer)
- 558
- 559 Although fluid bed dryers may differ from one another in geometry, operating
560 pressures, and other conditions, no fluidized solids bed dryer subclasses have
561 been identified.
562
- 563 d. Direct Heating, Dilute Solids Bed, Spray Dryer
- 564
- 565 Although spray dryers may differ from one another in geometry, operating
566 pressures, and other conditions, no spray dryer subclasses have been identified.
567
- 568 e. Direct Heating, Dilute Solids Bed, Flash Dryer
- 569
- 570 Although flash dryers may differ from one another in geometry, operating
571 pressures, and other conditions, no flash dryer subclasses have been identified.
572
- 573 f. Indirect Conduction Heating, Moving Solids Bed
- 574
- 575 Moving solids bed subclasses primarily are distinguished by the method or
576 technology for moving the solids bed.
577
- 578 • Paddle
 - 579 • Rotary (Tumble)
 - 580 • Agitation
- 581
- 582 g. Indirect Conduction Heating, Static Solids Beds
- 583
- 584 No indirect heating, static solids bed shelf dryer subclasses have been
585 identified.
586
- 587 h. Indirect Conduction, Lyophilization
- 588

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589 No lyophilizer subclasses have been identified.

590

591 i. Gas Stripping

592

593 Although gas stripping dryers may differ from one another in geometry, shape of
594 agitator, and how fluidizing gas is moved through the bed, no gas stripping dryer
595 subclasses have been identified.

596

597 j. Indirect Radiant Heating, Moving Solids Bed (Microwave Dryer)

598

599 Although microwave dryers may differ from one another in vessel
600 geometry and the way microwaves are directed into the solids, no
601 indirect radiant heating, moving solids bed dryer subclasses have been
602 identified.

603

604 Note: If a single piece of equipment is capable of performing multiple discrete unit operations
605 (mixing, granulating, drying), the unit was evaluated solely for its ability to dry. The drying
606 equipment was sorted into similar classes of equipment, based upon the method of heat transfer
607 and the dynamics of the solids bed.

608

E. Unit Dosing

610

1. Definitions

612

613 a. Unit Operation

614

615 Unit Dosing: The division of a powder blend into uniform single portions for
616 delivery to patients.

617

618 b. Operating Principles

619

620 i. Tableting

621

622 The division of a powder blend in which compression force is
623 applied to form a single unit dose.

624

625 ii. Encapsulating

626

627 The division of material into a hard gelatin capsule. Encapsulators
628 should all have the following operating principles in common:
629 rectification (orientation of the hard gelatin capsules), separation of
630 capsule caps from bodies, dosing of fill material/formulation,
631 rejoining of caps and bodies, and ejection of filled capsules.

632

633 iii. Powder Filling

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635 The division of a powder blend into a container closure system.

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636 2. *Equipment Classifications*

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a. Tablet Press

Tablet press subclasses primarily are distinguished from one another by the method that the powder blend is delivered to the die cavity. Tablet presses can deliver powders without mechanical assistance (gravity), with mechanical assistance (power assisted), by rotational forces (centrifugal), and in two different locations where a tablet core is formed and subsequently an outer layer of coating material is applied (compression coating).

- Gravity
- Power Assisted
- Centrifugal
- Compression Coating

Tablet press subclasses are also distinguished from one another for some special types of tablets where more than one hopper and precise powder feeding mechanism might be necessary.

- Micro/ mini tablet press
- Multi-layer tablet press (bi-layer, tri-layer)

b. Encapsulator

Encapsulator subclasses primarily are distinguished from one another by the method that is used for introducing material into the capsule. Encapsulators can deliver materials with a rotating auger, vacuum, vibration of perforated plate, tamping into a bored disk (dosing disk), or cylindrical tubes fitted with pistons (dosator).

- Auger
- Vacuum
- Vibratory
- Dosing Disk
- Dosator

c. Powder Filler

Subclasses of powder fillers primarily are distinguished by the method used to deliver the predetermined amount for container fill.

- Vacuum
- Auger

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681 **F. Soft Gelatin Capsule**

682

683 *1. Definitions*

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685 **a. Unit Operations**

686

687 **i. Gel Mass Preparation:** The manufacture of a homogeneous,
688 degassed liquid mass (solution) of gelatin, plasticizer, water, and
689 other additives, either in solution or suspension, such as colorants,
690 pigments, flavors, preservatives, etc., that comprise a unique
691 functional gel shell formation. The operation may be performed in
692 discreet steps or by continuous processing. Minor components can
693 be added after the liquid gel mass is made.

694

695 **ii. Fill Mixing:** The mixing of either liquids or solids with other liquids
696 to form a solution; blending of limited solubility solid(s) with a
697 liquid carrier and suspending agents used to stabilize the blend to
698 form a suspension; or the uniform combination of dry inert and drug
699 active substances to form a dry powder fill suitable for
700 encapsulation. The reader should refer to the other sections of this
701 document for dry fill manufacture.

702

703 **iii. Encapsulation:** The continuous casting of gel ribbons, with liquid
704 fill material being injected between the gel ribbons using a positive
705 displacement pump or, for dry materials being gravity or force fed
706 with capsule formation using a rotary die.

707

708 **iv. Washing:** The continuous removal of a lubricant material from the
709 outside of the formed capsule. The washing operation is unique to
710 each manufacturer's operation and generally uses in-house
711 fabricated equipment. This equipment will not be discussed in this
712 guidance document.

713

714 **v. Drying:** The removal of the majority of water from the capsule's
715 gel shell by tumbling and subsequent tray drying using conditioned
716 air, which enhances the size, shape, and shell physical properties of
717 the final product. The drying operation is unique to each
718 manufacturer's operation and generally uses in-house fabricated
719 equipment. This equipment will not be discussed in this guidance
720 document.

721

722 **vi. Inspection/Sorting:** The process wherein undesirable capsules are
723 removed, including misshapen, leaking, and unfilled capsules as
724 well as agglomerates of capsules.

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726 **vii. Printing:** The marking of a capsule surface for the purpose of
727 product identification, using a suitable printing media or method.

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b. Operating Principles

i. Mixing

The combination of solid and liquid components, including suspending aid(s) at either ambient or elevated temperatures to form a solution, suspension, or dry powder blend for the manufacture of gel mass or fill material. Mixing also includes the incorporation of minor components into the liquid gel mass.

ii. Deaggregation

The removal of aggregates using a suitable homogenizer/mill to provide a pumpable fill material. The procedure has minimal effect on the particle size distribution of the initial solid component(s), and is viewed as a processing aid.⁸

iii. Deaeration

The removal of entrapped air from either the gel mass or fill material, solution or suspension. This process can take place in either the mixing vessel, through the application of vacuum, or a separate off-line step.

iv. Holding

The storage of liquid gel mass or fill material in a vessel, with a mixer or without, prior to encapsulation, which also may be equipped with a jacket for either heating or cooling.

v. Encapsulation

The formation of capsules using a rotary die machine.⁹

vi. Inspection/Sorting

The physical removal of misshapen, leaking, or agglomerated capsules, using either a manual or automatic operation.

⁸ Carstensen, J. T., "Theory of Pharmaceutical Systems, Volume 11 Heterogeneous Systems," *Academic Press*, New York, NY, 1973, p 51.

⁹ Lachman, L., H. A. Lieberman, and J. L. Kanig (Eds.), *The Theory and Practice of Industrial Pharmacy*, Chapter 3, p. 359 (Stanley, J. P.), Philadelphia Lea & Febiger, 1971; Tyle, P. (Ed.), *Specialized Drug Delivery Systems, Manufacturing and Production Technology*, Chapter 10, p. 409 (Wilkinson, P.K. and F.S. Hom), New York; M. Dekker, 1990; Porter, S., *Remington's Pharmaceutical Sciences*, Edition 18, Chapter 89, pp. 1662 - 1665, Easton, Penn.: Mack Publishing Co.

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vii. Printing

The user of this document is asked to refer to the coating/printing section, in which the use of various pieces of equipment are defined and categorized.

2. *Equipment Classifications*

a. Mixers and Mixing Vessels

Mixer and mixing vessel subclasses primarily are distinguished by the mixing energy, mixer type, and whether a jacketed vessel with vacuum capabilities is used in conjunction with a specific mixer.

- Low Energy Mixer
- High Energy Mixer
- Planetary
- Jacketed Vessel With and Without Vacuum
- Conventional

b. Deaggregators

Deaggregator subclasses primarily are distinguished by the type of mechanical action imparted to the material.

- Rotor/Stator
- Roller
- Cutting Mills
- Stone Mills
- Tumbling Mills

c. Deaerators

Deaerator subclasses primarily are distinguished by the air removal path, either through the bulk or through a thin film, and whether it is a batch or in-line process.

- Vacuum Vessel
- Off Line/In Line

d. Holding Vessels

Although holding vessels may differ from one another, based upon whether they are jacketed, with and without integrated mixing capabilities, no holding vessel subclasses have been identified.

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- Jacketed vessel with and without mixing system

e. Encapsulators

Encapsulator subclasses primarily are distinguished by the method used to inject the fill material.

- Positive Displacement Pump
- Gravity or Force Fed

f. Inspection/Sorting

Inspection/sorting equipment subclasses primarily are distinguished by the method used to present the capsule for viewing and mechanical method of separation.

- Belt
- Vibratory
- Roller
- Rotary Table
- Electromechanical

G. Coating/Printing/Drilling

1. Definitions

a. Unit Operation

- i. Coating: The uniform deposition of a layer of material on or around a solid dosage form, or component thereof, to:
 - a. Protect the drug from its surrounding environment (air, moisture, and light), with a view to improving stability.
 - b. Mask unpleasant taste, odor, or color of the drug.
 - c. Increase the ease of ingesting the product for the patient.
 - d. Impart a characteristic appearance to the tablets, which facilitates product identification and aids patient compliance.
 - e. Provide physical protection to facilitate handling. This includes minimizing dust generation in subsequent unit operations.
 - f. Reduce the risk of interaction between incompatible components. This would be achieved by coating one or more of the offending ingredients.

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860 g. Modify the release of drug from the dosage form. This
861 includes delaying, extending, and sustaining drug substance
862 release.
863

864 The coating material deposition typically is accomplished
865 through one of five major techniques:
866

- 867 a. Sugar Coating - Deposition of coating material onto
868 the substrate from aqueous solution/suspension of
869 coatings, based predominately upon sucrose as a raw
870 material.
- 871 b. Film Coating - The deposition of polymeric film onto
872 the solid dosage form.
- 873 c. Core Enrobing - The gelatin coating of gravity or force
874 fed pre- formed tablets or caplets.
- 875 d. Microencapsulation - The deposition of a coating material
876 onto a particle, pellet, granule, or bead core. The
877 substrate in this application ranges in size from submicron
878 to several millimeters. It is this size range that
879 differentiates it from the standard coating described in 1
880 and 2 above.
- 881 e. Compression Coating (This topic is addressed in the Unit
882 Dosing section.)
883

- 884 ii. Printing: The marking of a capsule or tablet surface for the
885 purpose of product identification. Printing may be accomplished
886 by either the application of a contrasting colored polymer (ink)
887 onto the surface of a capsule or tablet, or by the use of laser
888 etching.
889

890 The method of application, provided the ink formulation is not
891 altered, is of no consequence to the physical-chemical properties of
892 the product.
893

- 894 iii. Drilling: The drilling or ablating of a hole or holes through the
895 polymeric film coating shell on the surfaces of a solid oral dosage
896 form using a laser. The polymeric film shell is not soluble in
897 vivo. The hole or holes allow for the modified release of the drug
898 from the core of the dosage form.
899

b. Operating Principles

- 900 i. Pan Coating

903 The uniform deposition of coating material onto the surface of a
904 solid dosage form, or component thereof, while being translated via
905 a rotating vessel.

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- ii. Gas Suspension

The application of a coating material onto a solid dosage form, or component thereof, while being entrained in a process gas stream.

Alternatively, this may be accomplished simultaneously by spraying the coating material and substrate into a process gas stream.
 - iii. Vacuum Film Coating

This technique uses a jacketed pan equipped with a baffle system. Tablets are placed into the sealed pan, an inert gas (i.e., nitrogen) is used to displace the air and then a vacuum is drawn.
 - iv. Dip Coating

Coating is applied to the substrate by dipping it into the coating material. Drying is accomplished using pan coating equipment.
 - v. Electrostatic Coating

A strong electrostatic charge is applied to the surface of the substrate. The coating material containing oppositely charged ionic species is sprayed onto the substrate.
 - vi. Compression Coating

Refer to the Unit Dosing section of this document.
 - vii. Ink-Based Printing

The application of contrasting colored polymer (ink) onto the surface of a tablet or capsule.
 - viii. Laser Etching

The application of identifying markings onto the surface of a tablet or capsule using laser-based technology.
 - ix. Drilling

A drilling system typically is a custom built unit consisting of a material handling system to orient and hold the solid dosage form, a laser (or lasers), and optics (lenses, mirrors, deflectors, etc.) to

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951 ablate the hole or holes, and controls. The drilling unit may include
952 debris extraction and inspection systems as well. The sorting,
953 orienting, and holding equipment commonly is provided by dosage
954 form printing equipment manufacturers, and is considered ancillary
955 in this use.

956

957 2. *Equipment Classification*

958

959 a. Pan Coating

960

961 Pan coating subclasses primarily are distinguished by the pan configuration, the
962 pan perforations, and/or the perforated device used to introduce process air for
963 drying purposes. Perforated coating systems include both batch and continuous
964 coating processes.

965

966 • Conventional Coating System

967 • Perforated Coating System

968

969 b. Gas Suspension

970

971 Gas suspension subclasses primarily are distinguished by the method
972 by which the coating is applied to the substrate.

973

974 • Fluidized Bed with bottom spray mechanism

975 • Fluidized Bed with tangential spray mechanism

976 • Fluidized Bed with top spray mechanism

977 • Fluidized Bed with Wurster column

978 • Spray Congealing/Drying

979

980 c. Vacuum Film Coating

981

982 Although there may be differences in the jacketed pan, baffle system, or
983 vacuum source, no vacuum film coating subclasses have been identified.

984

985 d. Dip Coating

986

987 Because of the custom design associated with this class of coating, no dip
988 coating subclasses or examples have been identified.

989

990 e. Electrostatic Coating

991

992 Because of the custom design associated with this class of coating, no
993 electrostatic coating subclasses or examples have been identified.

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995 f. Compression Coating

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997 Refer to the Unit Dosing section of this document.

998

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g. Ink-Based Printing

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1001 Ink-based printing subclasses primarily are distinguished by the method by which
1002 the marking is applied to a capsule or tablet surface.

1003

1004

- Offset

1005

- Ink Jet

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1007

h. Laser Etching (Printing)

1008

1009 Although laser etching systems may differ from one another, no laser
1010 etching subclasses have been identified.

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1012

i. Drilling

1013

1014 The method of producing the laser pulse that ablates the hole(s) is of no
1015 consequence to the physical-chemical properties of the product. Therefore, no
1016 dosage form drilling equipment subclasses have been identified.

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V. SUPAC-SS INFORMATION

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A. Particle Size Reduction/Separation

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1. Definitions

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a. Unit Operations

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- i. Particle Size Reduction: The mechanical process of breaking particles into smaller pieces via one or more size reduction mechanisms. The mechanical process used is generally referred to as milling.

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- a. Particle - Either a discrete particle or a grouping of particles, generally known as an agglomerate.

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- b. Particle Size Reduction Mechanisms

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- Compression - Particle size reduction by applying a force slowly (as compared to impact) to the particle surface toward the center of the particle.
 - Cutting - Particle size reduction by applying a shearing force to a material.
- ii. Particle Separation: Particle size classification according to particle size alone.

b. Operating Principles

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- i. Fluid Energy Milling: Particle size reduction by high-speed particle-to- particle impact and/or attrition (also known as micronizing).
 - ii. Impact Milling: Particle size reduction by high-speed mechanical impact or impact with other particles (also known as milling, pulverizing, or comminuting).
 - iii. Cutting: Particle size reduction by mechanical shearing.
 - iv. Compression Milling: Particle size reduction by compression stress and shear between two surfaces.
 - v. Screening: Particle size reduction by mechanically-induced attrition through a screen (commonly referred to as milling or deagglomeration).
 - vi. Tumble Milling: Particle size reduction by attrition, using grinding media.
 - vii. Separating: Particle segregation based on size alone, without any significant particle size reduction (commonly referred to as screening or bolting).

2. *Equipment Classifications*

a. Fluid Energy Mills

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Fluid energy mill subclasses have no moving parts and primarily differ in the configuration and/or shape of their chambers, nozzles, and classifiers.

- 1088
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- Fixed target
 - Fluidized bed
 - Loop and/or oval

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- Moving target
 - Opposed jet
 - Opposed jet with dynamic classifier
 - Tangential jet
- b. Impact Mills
- Impact mill subclasses primarily differ in the configuration of the grinding heads, chamber grinding liners (if any), and classifiers.
- Cage
 - Hammer air swept
 - Hammer conventional
 - Pin or disc
- c. Cutting Mills
- Although cutting mills can differ in whether the knives are movable or fixed, and in classifier configuration, no cutting mill subclasses have been identified.
- d. Compression Mills
- Although compression mills, also known as roller mills, can differ in whether one or both surfaces move, no compression mill subclasses have been identified.
- e. Screening Mills
- Screening mill subclasses primarily differ in the rotating element.
- Oscillating bar
 - Rotating impeller
 - Rotating screen
- f. Tumbling Mills
- Tumbling mill subclasses primarily differ in the grinding media used and whether the mill is vibrated.
- Ball media
 - Rod media
 - Vibrating
- g. Separators
- Separator subclasses primarily differ in the mechanical means used to induce particle movement.

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- 1138 • Centrifugal
- 1139 • Vibratory or shaker
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1142 Note: If a single piece of equipment is capable of performing multiple discrete unit operations,
1143 it has been evaluated solely for its ability to impact particle size or separation.

B. Mixing

1. Definitions

a. Unit Operation

1150 Mixing: The reorientation of particles relative to one another to achieve
1151 uniformity or randomness. This process can include wetting of solids by a liquid
1152 phase, dispersion of discrete particles, or deagglomeration into a continuous
1153 phase. Heating and cooling via indirect conduction may be used in this operation
1154 to facilitate phase mixing or stabilization.
1155

b. Operating Principles

- 1158
- 1159 i. Convection Mixing, Low Shear: Mixing process with a repeated
1160 pattern of cycling material from top to bottom, in which dispersion
1161 occurs under low power per unit mass through rotating low shear
1162 forces.
1163
- 1164 ii. Convection Mixing, High Shear: Mixing process with a repeated
1165 pattern of cycling material from top to bottom, in which dispersion
1166 occurs under high power per unit mass through rotating high shear
1167 forces.
1168
- 1169 iii. Roller Mixing (Milling): Mixing process by high mechanical
1170 shearing action where compression stress is achieved by passing
1171 material between a series of rotating rolls. This is commonly
1172 referred to as compression or roller milling.
1173
- 1174 iv. Static Mixing: Mixing process in which material passes through a
1175 tube with stationary baffles. The mixer is generally used in
1176 conjunction with an in-line pump.
1177

2. Equipment Classification

a. Convection Mixers, Low Shear

1181 This group normally operates under low shear conditions and is broken down by
1182 impeller design and movement. Design can also include a jacketed vessel to
1183 facilitate heat transfer.
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- Anchor or sweepgate
- Impeller
- Planetary

b. Convection Mixers, High Shear

This group normally operates only under high shear conditions. Subclasses are differentiated by how the high shear is introduced into the material, such as by a dispersator with serrated blades or homogenizer with rotor stator.

- Dispersator
- Rotor stator

c. Roller Mixers (Mills)

No roller mixer subclasses have been identified.

d. Static Mixers

No static mixer subclasses have been identified.

Note: If a single piece of equipment is capable of performing multiple discrete unit operations, it has been evaluated solely for its ability to mix materials.

C. Emulsification

1. Definitions

a. Unit Operation

Emulsification: The application of physical energy to a liquid system consisting of at least two immiscible phases, causing one phase to be dispersed into the other.

b. Operating Principles

- i. Low Shear Emulsification: Use of low shear energy using mechanical mixing with an impeller to achieve a dispersion of the mixture. The effectiveness of this operation is especially dependent on proper formulation.
- ii. High Shear Emulsification: Use of high shear energy to achieve a dispersion of the immiscible phases. High shear can be achieved by the following means:
 - a. Stirring the mixture with a high speed chopper or saw-tooth dispersator.

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- b. Passing the mixture through the gap between a high-speed rotor and a stationary stator.
 - c. Passing the mixture through a small orifice at high pressure (valve- type homogenizer) or through a small orifice at high pressure followed by impact against a hard surface or opposing stream (valve-impactor type homogenizer), causing sudden changes of pressure.

2. Equipment Classification

a. Low Shear Emulsifiers

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Although low shear emulsification equipment (mechanical stirrers or impellers) can differ in the type of fluid flow imparted to the mixture (axial-flow propeller or radial-flow turbines), no subclasses have been defined.

b. High Shear Emulsifiers

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Subclasses of high shear emulsification equipment differ in the method used to generate high shear.

- Dispersator
- Rotor stator
- Valve or pressure homogenizer

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Note: If a single piece of equipment is capable of performing multiple discrete unit operations, the unit has been evaluated solely for its ability to emulsify materials.

D. Deaeration

1. Definitions

a. Unit Operation

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Deaeration: The elimination of trapped gases to provide more accurate volumetric measurements and remove potentially reactive gases.

b. Operating Principles

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The use of vacuum or negative pressure, alone or in combination with mechanical intervention or assistance.

2. Equipment Classification

a. Deaerators

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1281 Deaerator subclasses differ primarily in their air removal paths, either through the
1282 bulk material or through a thin film, and in whether they use a batch or in-line
1283 process.
1284

- 1285 • Off-Line or in-line
- 1286 • Vacuum vessel

1287
1288 Note: If a single piece of equipment is capable of performing multiple discrete unit operations,
1289 it has been evaluated solely for its ability to deaerate materials.
1290

E. Transfer

1. Definition

a. Unit Operation

1295
1296 Transfer: The controlled movement or transfer of materials from one location to
1297 another.
1298

b. Operating Principles

- 1300 i. Passive: The movement of materials across a non-mechanically-
1301 induced pressure gradient, usually through conduit or pipe.
1302
- 1303 ii. Active: The movement of materials across a mechanically-
1304 induced pressure gradient, usually through conduit or pipe.
1305
1306
1307

2. Equipment Classification

a. Low Shear

1310
1311 Active or passive material transfer, with a low degree of induced shear
1312
1313

- 1314 • Diaphragm
- 1315 • Gravity
- 1316 • Peristaltic
- 1317 • Piston
- 1318 • Pneumatic
- 1319 • Rotating lobe
- 1320 • Screw or helical screw

b. High Shear

1322
1323 Active or mechanical material transfer with a high degree of induced shear
1324
1325

- 1326 • Centrifugal or turbine
- 1327 • Piston
- 1328 • Rotating gear

1329
1330 Note: This section is intended to deal with the transfer of shear sensitive materials, including
1331 product or partially manufactured product. A single piece of equipment can be placed in either a
1332 low or high shear class, depending on its operating parameters. If a single piece of equipment is
1333 capable of performing multiple discrete unit operations, the unit has been evaluated solely for its
1334 ability to transfer materials.

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F. Packaging

1. Definitions

a. Unit Operation

- i. Holding: The process of storing product after completion of manufacturing process and prior to filling final primary packs.
- ii. Transfer: The process of relocating bulk finished product from holding to filling equipment using pipe, hose, pumps and/or other associated components.
- iii. Filling: The delivery of target weight or volume of bulk finished product to primary pack containers
- iv. Sealing: A device or process for closing and/or sealing primary pack containers following the filling process.

b. Operating Principles

- i. Holding: The storage of liquid, semi-solids, or product materials in a vessel that may or may not have temperature control and/or agitation.
- ii. Transfer: The controlled movement or transfer of materials from one location to another.
- iii. Filling: Filling operating principles involve several associated subprinciples. The primary package can be precleaned to remove particulates or other materials by the use of ionized air, vacuum, or inversion. A holding vessel equipped with an auger, gravity, or pressure material feeding system should be used. The vessel may or may not be able to control temperature and/or agitation. Actual filling of the dosage form into primary containers can involve a metering system based on an auger, gear, orifice, peristaltic, or piston pump. A head-space blanketing system can also be used.
- iv. Sealing: Primary packages can be sealed using a variety of methods, including conducted heat and electromagnetic (induction or microwave) or mechanical manipulation (crimping or torquing).

2. Equipment Classification

a. Holders

Contains Nonbinding Recommendations

Draft — Not for Implementation

1383 Although holding vessels can differ in their geometry and ability to control
1384 temperature or agitation, their primary differences are based on how materials
1385 are fed.

1386

1387

- Auger

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- Gravity

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- Pneumatic (nitrogen, air, etc.)

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1391

b. Fillers

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The primary differences in filling equipment are based on how materials
1394 are metered.

1395

1396

- Auger

1397

- Gear pump

1398

- Orifice

1399

- Peristaltic pump

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- Piston

1401

1402

c. Sealers

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1404

The differences in primary container sealing are based on how energy is
1405 transferred or applied.

1406

1407

- Heat

1408

- Induction

1409

- Microwave

1410

- Mechanical or crimping

1411

- Torque

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